# **SERVO CONTROLLER - DIY**

- servo controller with LED indication

- the module commands 4 servos with 4 pushbuttons between 0 - 180 degrees

- fixed starting position (0 degrees)

- adjustable maximum angle of a servo with four onboard potentiometer

- adjustable speed of servos (one potentiometer for all servos)

- store position of servos into the memory (remembers the last position after power switched off)

- output for 8x LEDs, or 4x Bipolar LEDs

- the LEDs show the position of the servo; you will always know in which position the servo arm is

- example: if the LED is green the servo controlled turnout is in the straight position, if the LED is red it is in the divergent position

- suitable for manual control of turnouts, semaphores, moving any kind of arms, doors, barriers

- push button to move servo into one direction (clockwise), push once again to move the servo to the opposite direction (counterclockwise)

- recommended power supply: 8-12V AC/10-16 DC

#### SETTING:

- connect LED diodes to left green terminal (picture 4, 5 and 6)

- the LED polarity is not important. Be careful that one of them must be contrary to the other one! If you would like to change the colors (red=straight, green=divergent), replace the +5V and 0V (ground) on LED's legs

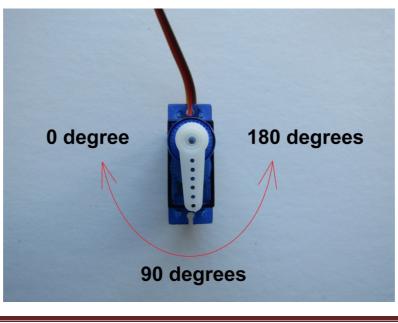
- connect the servo to the first output (left pinhead). Be careful of the servo polarity orientation!

- move the servo to the start position (0 degree - clockwise - picture 1) with the first pushbutton

- move potentiometer with a small flat screwdriver

- press the first pushbutton to test the range of servo

- continue to set other outputs



Servo controller ©Szabi

### Outputs

- X1.1 LED1 X1.2 - LED2 X1.3 - LED3 X1.4 - LED4 X1.5 - GND (output) X1.6 - +5V (output)
- X2.1 10-12V AC/DC (input) X2.2 - 10-12V AC/DC (input) X2.3 - Button 1 X2.4 - Button 2 X2.5 - Button 3 X2.6 - Button 4 X2.7 - Common GND (all buttons)

## Components

R1 R2	2k7 150R
R3	820R
R4	10k / 0,66W
IC1	LM350
IC2	Atmega328P-PU with program
IC1 socket	28 pins, narrow
U1	W10M
CR1	16 MHz crystal
D1	SB260
C1	1000uF/35V
C2	100uF/25V
C3, C4	100nF
C5, C6	22pF / SMD1206
P1 - P4	RM065 - 10k
X1	3.5 mm terminal block, 6 pins
X2	3.5 mm terminal block, 7 pins
X3 - X6	pinhead, male, 3 pins, RM 2,54 mm
heatsink radiator	TO220 (IC1)

## **IMPORTANT**:

Always switch off the power supply before connect or disconnect servo or push button!

